

Structure of the Primary Hamiltonian Constraints for a Singular N -Body Lagrangian

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The structure of the primary Hamiltonian constraints is examined for a simple singular Lagrangian form (N interacting particles). The problem is a straightforward generalization of well-known two-particle cases.

1. INTRODUCTION AND NOTATION

In a given frame of reference Σ we assume there are $N \geq 1$ point particles; that is, a total of $4N$ "position" coordinates

$$\begin{aligned} x_{(i)}^\mu, \quad \mu = 0, 1, 2, 3 \text{ (axis label)} \\ i = 1, 2, \dots, N \text{ (particle label)} \end{aligned} \quad (1)$$

We define the generalized coordinates

$$q_j^\mu = \alpha_j^i x_{(i)}^\mu; \quad i, j = 1, 2, \dots, N \quad (2)$$

where (α_j^i) is a constant nonsingular matrix. (Note the summation of repeated up and down indices.) For a simpler notation, we also introduce the symbol $Q = \{Q^A\}$, $A = 1, 2, \dots, 4N$, defined by

$$\{Q^A\} = \{q_j^\mu\} \quad (3)$$

For example, one can choose

$$\begin{aligned} Q^1 = q_1^0, \dots, \quad Q^4 = q_1^3 \\ Q^{4N-3} = q_N^0, \dots, \quad Q^{4N} = q_N^3 \end{aligned} \quad (4)$$

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2. LAGRANGIAN AND CONSTRAINTS

Assuming that the (isolated) system can be described with respect to an evolution parameter τ (Kalb and Van Alstine, 1976; Raspini, 1983), we now consider a reparametrization-invariant Lagrangian L (Kalb and Van Alstine, 1976; Bolza, 1904). The simplest form, modeled on the relativistic single-particle case, is clearly

$$L = -[\dot{Q}^A G_{AB}(Q) \dot{Q}^B]^{1/2}; \quad G_{AB} = G_{BA} \quad (5)$$

$$\dot{Q}^A = \frac{dQ^A}{d\tau}; \quad A, B = 1, 2, \dots, 4N$$

The Lagrangian in (5) is singular, and the corresponding Legendre Hamiltonian is identically vanishing (Kalb and Van Alstine, 1976; Bolza, 1904). A Dirac-type treatment must then be applied (Kalb and Van Alstine, 1976; Raspini, 1983) if one wishes to obtain an appropriate Hamiltonian formulation. Of course, before starting this approach, one should restrict the (\dot{Q}, Q) space according to

$$\dot{Q}^A G_{AB} \dot{Q}^B > 0 \quad (6)$$

which is the regularity condition for L .

From L , we define the P canonical momenta:

$$P_A = -\partial L / \partial \dot{Q}^A = G_{AB} S^B \quad (7a)$$

$$S^B = -\dot{Q}^B / L \quad (7b)$$

Momenta are not all independent, and some "primary constraints" exist among them (Kalb and Van Alstine, 1976, Raspini, 1983; Dirac, 1964; Shanmugadhasan, 1973; Sudarshan and Mukunda, 1974). The precise number of constraints depends on the rank of (G_{AB}) . We then select a part of the Q space where this rank is constant:

$$\text{rank} [G_{AB}(Q)] = R; \quad 0 < R \leq 4N \quad (8)$$

For our chosen R , the treatment is applied in the (\dot{Q}, Q) region identified by equations (6) and (8).

When the rank of (G_{AB}) is R , there are $4N - R$ independent vectors $V_l(Q)$ such that

$$G_{BA} V_l^A = 0; \quad l = 1, 2, \dots, 4N - R \quad (9)$$

Therefore, the first $4N - R$ primary constraints can be written as

$$P_A V_l^A(Q) = 0 \quad (10)$$

At this point, one has already introduced all the constraints that are needed to take into account the functional interdependence of the P_A with respect to the variables S^B [equation (7a)]. In fact

$$\partial P_A / \partial S^B = G_{AB} \quad (11)$$

The next step is to examine equation (7b), which is also not invertible (that is, the \dot{Q} variables cannot be solved as functions of the S variables).

It is readily seen that equation (7b) implies the identity

$$S^A G_{AB} S^B = 1 \quad (12)$$

In terms of the P variables, this is equivalent to the primary constraint

$$P_A H^{AB}(Q) P_B = 1 \quad (13)$$

where (H^{AB}) is any of the matrices such that

$$G_{AC} H^{CD} G_{DB} = G_{AB}, \quad A, B, C, D = 1, 2, \dots, 4N \quad (14)$$

Clearly, the relationship expressed by (13) has the structure of an Einstein condition. (That is, a quadratic expression of the momenta being equal to a constant.) Furthermore, the same equation can be considered as a straightforward generalization of well-known two-particle cases. In such cases, the choice for G_{AB} is

$$G_{AB}(Q) = G_{AB}^{\text{free}}(Q) V(Q) \quad (15)$$

where G_{AB}^{free} is suitable for free particles, and V plays the role of the "multiplicative potential" (Kalb and Van Alstine, 1976).

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